

Outline:

- 1) cross product structures
- 2) G_2 -structures - compared with Kähler
- 3) Decomposition of Λ^*
- 4) Deformations -
 - 1) conformal
 - 2) infinitesimal - by a V.F.
 - 3) non-infinitesimal by a V.F.

① on $\mathbb{R}^n, \langle, \rangle$

$$X : \underbrace{\mathbb{R}^n \times \dots \times \mathbb{R}^n}_k \rightarrow \mathbb{R}^n, \quad k\text{-linear and alternating}$$

is a cross product if

$$(i) \langle X(u_1, \dots, u_k), u_i \rangle = 0 \quad \forall i=1, \dots, k$$

$$(ii) |X(u_1, \dots, u_k)|^2 = |u_1 \wedge \dots \wedge u_k|^2$$

Note: from X
you get a $(k+1)$ -form
 α_i
 $\alpha(u_1, \dots, u_{k+1}) =$
 $\langle X(u_1, \dots, u_k), u_{k+1} \rangle$

Classified by Brown & Gray (1967)

(i) $k=n-1$

$$X(u_1, \dots, u_{n-1}) = *(u_1 \wedge \dots \wedge u_{n-1})$$

$\alpha =$ volume form

(ii) $n=2m \quad k=1 \quad J: \mathbb{R}^{2m} \hookrightarrow \mathbb{R}^{2m}, \quad J^2 = -I, \quad \text{an a.c. str.},$

$\alpha = \omega$ Kähler form

(iii) $n=7 \quad k=2$

G_2 structure

$\alpha = \psi, 3\text{-form}$

(iv) $n=8 \quad k=3$

$Spin_7$ structure $\alpha = \Phi, 4\text{-form}$

Define: M 7-mfd

G_2 -structure on M is a ~~globally defined, smoothly~~
smooth 3-form which is everywhere non-degenerate.

This defines a cross-product and metric globally.

In \mathbb{R}^7 :

$$u \times (u \times v) = -|u|^2 v + \langle u, v \rangle u$$

IF φ is a 3-form defining a G_2 -structure

$$(v \lrcorner \varphi) \wedge (v \lrcorner \varphi) \wedge \varphi = -6|v|^2 \text{vol}$$

$$\langle u \times v, w \rangle = \varphi(u, v, w)$$

this is the definition of non-degenerate

②

Kähler J

$$\omega(u, v) = \langle Ju, v \rangle$$

g & J are independent

The manifold is Kähler ~~if~~ ~~iff~~

$$\Leftrightarrow \nabla J = 0$$

$$\Leftrightarrow \nabla \omega = 0$$

$$\Leftrightarrow \text{Hol} \subset U(m)$$

Equivalently: J integrable & $d\omega = 0$

Not all Ricci Flat

G_2 X

$$\varphi(u, v, w) = \langle u \times v, w \rangle$$

φ (or X) determines g

The manifold is a G_2 -manifold

$$\Leftrightarrow \nabla X = 0$$

$$\Leftrightarrow \nabla \varphi = 0$$

$$\Leftrightarrow \text{Hol} \subset G_2$$

Equivalently $d\varphi = 0$

$$d *_p \varphi = 0$$

All are Ricci Flat

← non-linear PDE since $*$ depends on φ .

Kähler \rightarrow Kähler + Ricci = 0 To obtain holonomy $\subset SU(n)$

$U(n) \rightarrow SU(n)$
1 dim

(3)

(Thm) Calabi-Yau: Given a compact, simply connected Kähler manifold (M, ω)
1978

$\exists!$ Ricci-flat Kähler metric in the same
Kähler class $\Leftrightarrow c_1 = 0$

Idea of Pf: Use $\partial\bar{\partial}$ -lemma: $\tilde{\omega} = \omega + \partial\bar{\partial}f$ ^{get} \rightarrow an elliptic PDE for f . (complex) Monge-Ampère equation.
Then prove existence and uniqueness of solutions.
This is a hard analysis problem.

To get Hol $\subset G_2$, no intermediate starting pt.

$SO(7) \rightarrow G_2$

21 \rightarrow 14

difference is
7 dimensions

"expect" a PDE for a V.F.
or a 1-form

Here there is no " $\partial\bar{\partial}$ -lemma".

Let φ_0 be a fixed G_2 -structure.

Given φ_0 , consider $\tilde{\varphi} = \varphi_0 + \eta$ for some 3-form η .

We want to study when $\tilde{\varphi}$ is a new G_2 -structure
and what its properties are in terms of φ_0 .

Simplest possibility: $\tilde{\varphi} = f^3 \varphi_0$ f non-vanishing (Gray) (5)

$$\Rightarrow \tilde{g} = f^2 g_0$$

Fernandez
Cabrera
Ugarte

$$d\varphi \in \Lambda^4_1 \oplus \Lambda^4_7 \oplus \Lambda^4_{27}$$

$$d*\varphi \in \Lambda^5_7 \oplus \Lambda^5_{17}$$

$\tau_1 \in \Lambda^4_7$ is isomorphic to
component of $d\varphi$ in Λ^4_7
 \cong component of
 $d*\varphi$ in Λ^5_7

Conformally can eliminate τ_1 .

Now consider infinitesimal deformations in the Λ^3_7 -direction:

consider φ_t s.t.

$$\frac{d}{dt} \varphi_t = W \lrcorner *_{t} \varphi_t \quad \text{for fixed } W \in \Gamma(TM)$$

it looks nonlinear but in fact, under this flow the
metric doesn't change, $g_t = g_0 = \text{const.}$
so $*_{t} = *_{0}$

$$\text{so } \frac{d}{dt} \varphi_t = W \lrcorner *_{0} \varphi_t$$

$$\text{The solution is } \varphi_t = \varphi_0 + \frac{(1 - \cos(|w|t))}{|w|^2} (W \lrcorner * (W \lrcorner * \varphi_0)) \\ + \frac{\sin(|w|t)}{|w|} (W \lrcorner * \varphi_0)$$

This yields, for each choice of vector field w ,
 a closed path of \mathbb{R} pos. 3-forms, all with same metric. (Implicit in Bryant-Salamon 89)

Special Case:

i) $N = \mathbb{C}P^3$ 3-fold (Ω, w)

$$M = N \times S^1$$

$$\varphi = \operatorname{Re}(\Omega) - d\theta \wedge w \quad \text{is a } G_2\text{-structure.}$$

Let $w = \frac{\partial}{\partial \theta}$ then

$$\varphi_t = \operatorname{Re}(e^{it} \Omega) - d\theta \wedge w$$

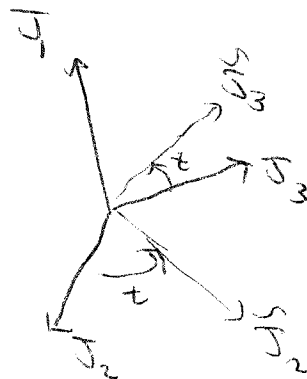
this is the phase freedom for the holomorphic $(n,0)$ -form.

ii) $L = K^3$ w_1, w_2, w_3 (Hyperkähler ~~dim~~ $\dim_{\mathbb{C}} = 2$)

$$M = L \times T^3 \quad \varphi = d\theta_1 \wedge d\theta_2 \wedge d\theta_3 - \sum_{i=1}^3 d\theta_i \wedge w_i \quad \text{is a } G_2\text{-structure}$$

$$\varphi_t = d\theta^1 \wedge d\theta^2 \wedge d\theta^3 - d\theta^1 \wedge w_1 - d\theta^2 \wedge [(\cos t)w_2 + \sin t w_3] - d\theta^3 \wedge [(-\sin t)w_2 + (\cos t)w_3]$$

This is a hyperkähler rotation by angle t around J_1 axis.



Try

non-infinitesimal v.f. deformation:

(7)

$$W \in \Gamma(TM)$$

$$\tilde{\varphi} = \varphi_0 + \underbrace{W \lrcorner * \varphi_0}_{\Lambda^3}$$

a priori, this may not be a G_2 structure.

Thm: (K-) $\tilde{\varphi}$ is still a positive 3-form

The new metric $\langle \cdot, \cdot \rangle_{\tilde{\nu}}$ is

$$\begin{aligned} \langle V_1, V_2 \rangle_{\tilde{\nu}} &= \frac{1}{(1+|W|_0^2)^{1/3}} \left(\langle V_1, V_2 \rangle_0 + \langle W \times V_1, W \times V_2 \rangle_0 \right) \\ &= \frac{1}{(1+|W|_0^2)^{1/3}} \left[\langle V_1, V_2 \rangle_0 + |W|_0^2 \langle V_1, V_2 \rangle_0 - \langle W, V_1 \rangle_0 \langle W, V_2 \rangle_0 \right] \end{aligned}$$

\uparrow
 with old
 cross product

Geometrically:

if $V_i = k; w$
($w \times w = 0$)

$$\langle V_1, V_2 \rangle_{\tilde{\nu}} = \frac{1}{(1+|W|_0^2)^{1/3}} \langle V_1, V_2 \rangle_0$$

metric shrinks in W direction

if V_1 or $V_2 \perp w$

$$\langle V_1, V_2 \rangle_{\tilde{\nu}} = (1+|W|_0^2)^{2/3} \langle V_1, V_2 \rangle_0$$

expands in
other 6 ~~directions~~
directions.

The new dual 4-form is:

$$\tilde{*} \tilde{\varphi} = (1 + |W|_0^2)^{-\frac{1}{3}} \left[* \varphi_0 + * (W \lrcorner * \varphi_0) + W \lrcorner * (W \lrcorner \varphi_0) \right] \quad (8)$$

$$\tilde{\varphi} = \varphi_0 + W \lrcorner * \varphi_0$$

probably
elliptic
in certain
cases

$$\left[\begin{array}{l} d\tilde{\varphi} = 0 \Leftrightarrow d(W \lrcorner * \varphi_0) = -d\varphi \\ d\tilde{*}\tilde{\varphi} = 0 \Leftrightarrow \text{non-linear PDE for } W \end{array} \right. \left. \begin{array}{l} \text{linear 49 eqns.} \\ 7 \text{ fncs.} \\ \text{overdetermined} \end{array} \right.$$

Similar results hold in the $Spin_7$ case.

$$Spin_7: \quad \Phi \in \Lambda^4 = \Lambda_1^4 \oplus \Lambda_7^4 \oplus \Lambda_{27}^4 \oplus \Lambda_{35}^4$$

$$d\Phi \in \Lambda_8^5 \oplus \Lambda_{48}^5$$

conformal scaling eliminates this

Consider $\tilde{\Phi} = \Phi_0 + \eta_7$, similar results hold as in G_2 case.