

Metric measure spaces with Ricci lower bounds, Lecture 2

Andrea Mondino (Zurich University)

MSRI-Berkeley
22th January 2016

Isoperimetric problem

One of oldest problems in mathematics, roots in myths of 2000 years ago (Queen Dido's problem). Roughly 3 questions:

- Q1 Given a space X what is the minimal amount of area needed to enclose a fixed volume $v > 0$?
- Q2 Is there an optimal shape?
- Q3 Describe/characterize the optimal shapes.

Examples

Not many examples of spaces X where we can fully answer Q1,Q2,Q3:

- ▶ $X = \mathbb{R}^n \rightsquigarrow$ only optimal shapes are round balls: $|\partial E| \geq |\partial B|$ where B is a round ball s.t. $|B| = |E|$.
- ▶ $X = S^n$ or $X = H^n$ analogous: only optimal shapes are metric balls: $|\partial E| \geq |\partial B|$ where B is a metric ball s.t. $|B| = |E|$
- ▶ Not many other examples (e.g. $\mathbb{R}P^3$ by Ritoré-Ros): in general the spaces for which we can fully answer Q1,Q2,Q3 are either very symmetric or perturbations of very symmetric spaces.
- ▶ Results in presence of mild singularities but still very symmetric (conical manifolds: Morgan-Ritoré '02, Milman-Rotem '14. Polytopes: Morgan '07).

Levy-Gromov inequality

Besides the euclidean one, probably the most famous isoperimetric inequality is the Levy-Gromov isoperimetric inequality:

Levy-Gromov Isoperimetric inequality

Let (M^n, g) Riemannian manifold with $Ric_g \geq Kg$, $K > 0$, and $E \subset M$ domain with smooth boundary ∂E . Then

$$\frac{|\partial E|}{|M|} \geq \frac{|\partial B|}{|S|} \quad (LGI)$$

where $S = S_K^n$ round sphere with $Ric \equiv K$, and $B \subset S$ is a spherical cap s.t. $\frac{|E|}{|M|} = \frac{|B|}{|S|}$.

Isoperimetry in m.m.s.

DEF: Let (X, d, m) be a m.m.s. with $m(X) = 1$ and let $E \subset X$ be a Borel set. Define the **outer Minkowski content**

$$m^+(E) := \liminf_{\varepsilon \rightarrow 0^+} \frac{m(E^\varepsilon) - m(E)}{\varepsilon}$$

where $E^\varepsilon := \{x \in X : d(x, E) < \varepsilon\}$

DEF: The **isoperimetric profile function** $\mathcal{I}_{(X, d, m)} : [0, 1] \rightarrow \mathbb{R}^+$ is the largest function such that $m^+(E) \geq \mathcal{I}_{(X, d, m)}(m(E)) \forall E \subset X$, i.e.

$$\mathcal{I}_{(X, d, m)}(v) := \inf\{m^+(E) \text{ s.t. } m(E) = v\}.$$

RK: - Q1 amounts to compute/estimate $\mathcal{I}_{(X, d, m)}$.

- (LGI) states $\mathcal{I}_{(M^n, d_g, \text{vol}/(\text{vol}(M)))} \geq \mathcal{I}_{(S_K^n, d_{g_{S_K^n}}, \text{vol}_{S_K^n}/(\text{vol}_{S_K^n}(S_K^n)))}$

Q: - is there an analog of (LGI) for $\text{Ric} \geq K$, $K \leq 0$?

-what about the (LGI) in $\text{RCD}(K, N)$ spaces?

Extension of (LGI) by E. Milman to arbitrary weighted manifolds and to $K \in \mathbb{R}$

DEF: Let (M^n, g) be a Riemannian manifold and let $\mathfrak{m} := \Psi \text{vol}_g$ for some smooth function $\Psi \geq 0$. We say that (M^n, g, \mathfrak{m}) satisfies the **CDD(K, N, D) condition** if

- ▶ $\text{supp}(\mathfrak{m}) \subset \Omega$ for some $\Omega \subset X$ geodesically convex with $\text{diam}(\Omega) \leq D$.
- ▶ $\text{Ric}_{g, \Psi, N} := \text{Ric}_g - (N - n) \frac{\nabla^2 \Psi^{1/N-n}}{\Psi^{N-n}} \geq Kg$

THM[E. Milman '12] For every $K \in \mathbb{R}, N, D > 0$ there exists an explicit function $\mathcal{I}_{K, N, D} : [0, 1] \rightarrow \mathbb{R}^+$ such that if (M^n, g, Ψ) satisfies **CDD(K, N, D)** then $\mathcal{I}_{(M^n, d_g, \Psi \text{vol})} \geq \mathcal{I}_{K, N, D}$.

RK: -for $K > 0, N = n \in \mathbb{N}$ and $D \geq \text{diam}(S_K^n)$, one re-obtains (LGI) since in this case $\mathcal{I}_{K, N, D} = \mathcal{I}_{(S_K^n, d_{S_K^n}, \text{vol}_{S_K^n} / (\text{vol}_{S_K^n}(S_K^n)))}$.

- for $K \leq 0$ there is not a model space as in (LGI), nevertheless there is a model isoperimetric profile function defined piecewise in an explicit way.

Extension to $RCD(K, N)$ spaces

THM[Cavalletti-M. '15] Levy-Gromov-Milman isoperimetric inequality holds in $RCD(K, N)$ spaces, i.e.

if (X, d, \mathfrak{m}) is an $RCD(K, N)$ space with $\mathfrak{m}(X) = 1$ and $\text{diam}(X) \leq D$ then $\mathcal{I}_{(X, d, \mathfrak{m})} \geq \mathcal{I}_{K, N, D}$.

COR: If (X, d, \mathfrak{m}) , with $\mathfrak{m}(X) = 1$, is an $RCD(K, N)$ space for some $K > 0$ and $2 \leq N \in \mathbb{N}$ then (LGI) holds, i.e. for every Borel subset $E \subset X$

$$\mathfrak{m}^+(E) \geq \frac{|\partial B|}{|S|}$$

where $S = S_K^N$ round sphere with $\text{Ric} \equiv K$, and $B \subset S$ is a spherical cap s.t. $\mathfrak{m}(E) = \frac{|B|}{|S|}$.

RK: Seems new even for Ricci limit spaces and Alexandrov spaces (sketch of proof by Petrunin in $\text{curv} \geq 1$)

Proof part 1: 1-D localization

Assume for the moment that given $E \subset X$ we can find a "1-D localization" $\{X_q\}_{q \in Q}$ of X , i.e.

1. $\{X_q\}_{q \in Q}$ is a partition of X , i.e. $X = \dot{\bigcup}_{q \in Q} X_q$,
2. $\mathfrak{m} = \int_Q \mathfrak{m}_q \alpha(dq)$, with $\alpha(Q) = 1$ and $\mathfrak{m}_q(X_q) = \mathfrak{m}_q(X) = 1$ for α -a.e. $q \in Q$
 \rightsquigarrow disintegration of \mathfrak{m} (kind of non-straight Fubini)
3. X_q is a geodesic in X and $(X_q, |\cdot|, \mathfrak{m}_q)$ is a $CD(K, N)$ space
4. $\mathfrak{m}_q(E \cap X_q) = \mathfrak{m}(E)$, for α -a.e. $q \in Q$,

RK the first two assumptions are mild, the characterizing properties are the last two.

Proof part 2: conclusion

If for every given $E \subset X$ we can find a 1-D localization as above then

$$\begin{aligned} \mathfrak{m}^+(E) &= \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}(E^\varepsilon) - \mathfrak{m}(E)}{\varepsilon} \\ &= \liminf_{\varepsilon \rightarrow 0^+} \int_Q \frac{\mathfrak{m}_q(E^\varepsilon) - \mathfrak{m}_q(E)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}_q(E^\varepsilon \cap X_q) - \mathfrak{m}_q(E \cap X_q)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \mathfrak{m}_q^+(E \cap X_q) \alpha(dq), \text{ by } E^\varepsilon \cap X_q \supset (E \cap X_q)^\varepsilon \cap X_q \\ &\geq \int_Q \mathcal{I}_{K,N,D}(\mathfrak{m}_q(E)) \alpha(dq) \text{ by 3. + Smooth LGMI} \\ &= \int_Q \mathcal{I}_{K,N,D}(\mathfrak{m}(E)) \alpha(dq) \text{ by 4.} = \mathcal{I}_{K,N,D}(\mathfrak{m}(E)). \end{aligned}$$

Proof part 3: how to construct a 1-D localization

- ▶ Recall that $m(X) = 1$, fix $E \subset X$ with $m(E) \in (0, 1)$,
- ▶ Let $\mu_0 := \frac{\chi_E}{m(E)} m$ and $\mu_1 := \frac{1-\chi_E}{1-m(E)} m = \frac{\chi_{X \setminus E}}{m(X \setminus E)} m$
- ▶ Consider the L^1 -optimal transport problem

$$\inf \left\{ \int_{X \times X} d(x, y) d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

- ▶ By Optimal Transport techniques there exists a minimizer $\gamma \in \mathcal{P}(X \times X)$ and a 1-Lipschitz function $\varphi : X \rightarrow \mathbb{R}$ called Kantorovich potential such that, denoted

$$\Gamma := \{(x, y) \in X \times X : \varphi(x) - \varphi(y) = d(x, y)\},$$

γ is concentrated on Γ .

- ▶ The relation \sim on X given by $x \sim y$ iff $(x, y) \in \Gamma$ or $(y, x) \in \Gamma$ is an equivalence relation on X (up to an m -negligible subset) and the equivalence classes are geodesics.
 \rightsquigarrow partition of X into geodesics driven by E
- ▶ More work to prove properties 3. and 4.

Why L^1 -transport?

- ▶ It is more standard to consider the L^2 -optimal transport problem: given $\mu_0, \mu_1 \in \mathcal{P}(X)$ let

$$\inf \left\{ \int_{X \times X} d(x, y)^2 d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}.$$

Which defines a metric W_2 on $\mathcal{P}(X)$.

- ▶ Now if $(\mu_t)_{t \in [0,1]}$ is a W_2 geodesic from μ_0 to μ_1 we know that μ_t is concentrated on midpoints of geodesics from $\text{supp}(\mu_0)$ to $\text{supp}(\mu_1)$:
 $\mu_t(\{\gamma(t) : \gamma \text{ geod}, \gamma(0) \in \text{supp}(\mu_0), \gamma(1) \in \text{supp}(\mu_1)\}) = 1,$
- ▶ moreover, from d^2 -monotonicity, if γ_1 and γ_2 are such geodesics with $\gamma_1(0) \neq \gamma_2(0)$ then $\gamma_1(t) \neq \gamma_2(t)$ in a.e. sense.
 \rightsquigarrow the transport at time t is given by a map (Brenier map).
- ▶ **BUT** it may happen $\gamma_1(s) = \gamma_2(t)$ for $s \neq t$
 \rightsquigarrow L^2 -transport does not induce an equivalence relation.
- ▶ On the other hand L^1 transport does induce an equivalence relation into rays where the transport is performed
 \rightsquigarrow partition of the space into $1D$ objects.

Brief history of 1-D localization technique

The localization technique is a way to reduce an a-priori complicated high dimensional problem to a simpler 1-dimensional problem.

- ▶ In \mathbb{R}^n or S^n , using the high symmetry of the space, 1-D localizations can be usually obtained via iterative bisections
 - ▶ Roots in a paper by Payne-Weinberger '60 about sharp estimate of 1st eigenvalue of Laplacian
 - ▶ Formalized by Gromov-V. Milman '87, Kannan - Lovász - Simonovits '95
- ▶ Extended by B. Klartag '14 to Riemannian manifolds via L^1 -optimal transport: no symmetry but still heavily using the smoothness of the space (estimates on 2^{nd} fundamental form of level sets of the Kantorovich potential φ)
- ▶ Extension to non-smooth spaces by Cavalletti-M. '15.

Rigidity of (LGI)

- ▶ It is well known that in smooth setting (LGI) are rigid:
if (M^n, g) has $Ric_g \geq (n-1)g$ and if there exists $v \in (0, 1)$
such that $\mathcal{I}_{(M^n, d_g, vol/(vol(M)))}(v) = \mathcal{I}_{(S^n, d_{g_{S^n}}, vol_{S^n}/(vol_{S^n}(S^n)))}(v)$
then M is isometric to S^n .
- ▶ Q: is it true also for non smooth spaces?
- ▶ **NO**: spherical suspensions have the same isoperimetric profile
function of the round sphere.
- ▶ Q: are spherical suspensions the only cases? YES!

THM (Cavalletti-M. '15) If (X, d, m) is an $RCD(N-1, N)$ space and there exists $v \in (0, 1)$ such that $\mathcal{I}_{(X, d, m)}(v) = \mathcal{I}_{N-1, N, \pi}(v)$,

Then (X, d, m) is a spherical suspension: $X \simeq [0, \pi] \times_{\sin}^{N-1} Y$ as m.m.s. for some $RCD(N-2, N-1)$ space (Y, d_Y, m_Y)

Moreover, in this case, the following hold:

- i)* For every $v \in [0, 1]$ it holds $\mathcal{I}_{(X, d, m)}(v) = \mathcal{I}_{N-1, N, \infty}(v)$. \rightsquigarrow Q1
- ii)* For every $v \in [0, 1]$ there exists a Borel subset $A \subset X$ with $m(A) = v$ such that $m^+(A) = \mathcal{I}_{(X, d, m)}(v) = \mathcal{I}_{N-1, N, \pi}(v)$.
 \rightsquigarrow Q2
- iii)* If $m(A) \in (0, 1)$ then $m^+(A) = \mathcal{I}_{(X, d, m)}(v) = \mathcal{I}_{N-1, N, \pi}(v)$ if and only if $\bar{A} = \{(t, y) \in [0, \pi] \times_{\sin}^{N-1} Y : t \in [0, r_v]\}$ or $\bar{A} = \{(t, y) \in [0, \pi] \times_{\sin}^{N-1} Y : t \in [\pi - r_v, \pi]\}$, where \bar{A} is the closure of A and $r_v \in (0, \pi)$ is chosen so that $\int_{[0, r_v]} c_N(\sin(t))^{N-1} dt = v$, c_N being given by $c_N^{-1} := \int_{[0, \pi]} (\sin(t))^{N-1} dt$. \rightsquigarrow Q3

Proof of rigidity

- ▶ The idea is to show that $\text{diam}(X) = \pi$ and then apply Cheng-Ketterer Maximal Diameter Theorem which gives that X is a spherical suspension.
- ▶ Assume by contradiction there exists $\bar{v} \in (0, 1)$ such that $\mathcal{I}_{(X,d,m)}(\bar{v}) = \mathcal{I}_{N-1,N,\pi}(\bar{v})$ but $\text{diam}(X) \leq \pi - \varepsilon_0 < \pi$.
- ▶ Key observation: there exists $\delta > 0$ such that $\mathcal{I}_{N-1,N,\pi}(\bar{v}) \leq \mathcal{I}_{N-1,N,D}(\bar{v}) - \delta$ for every $D \in (0, \pi - \varepsilon_0]$.
- ▶ Let now $E \subset X$ be such that $m(E) = \bar{v}$ and $m^+(E) \leq \mathcal{I}_{(X,d,m)}(\bar{v}) + \frac{\delta}{2} = \mathcal{I}_{N-1,N,\pi}(\bar{v}) + \frac{\delta}{2}$.
- ▶ Arguing as in the proof of the isoperimetric inequality by 1-D localization associated to E we get

$$\begin{aligned} \mathcal{I}_{N-1,N,\pi}(\bar{v}) + \frac{\delta}{2} &\geq m^+(E) \geq \int_Q m_q^+(E \cap X_q) \alpha(dq) \\ &\geq \int_Q \mathcal{I}_{N-1,N,|\text{diam}(X_q)|}(\bar{v}) \alpha(dq) \text{ by } m_q(E) = \bar{v} \\ &\geq \mathcal{I}_{N-1,N,\pi}(\bar{v}) + \delta \text{ by } \text{diam}(X_q) \leq \text{diam}(X) \end{aligned}$$

Almost rigidity of (LGI)

Q: what happens if $\mathcal{I}_{(X,d,m)}$ is close to the model $\mathcal{I}_{N-1,N,\pi}$? Does it imply (X, d, m) close to a spherical suspension?

THM(Cavalletti-M.'15) For every $N \in [2, \infty)$, $\nu \in (0, 1)$, $\varepsilon > 0$ there exists $\bar{\delta} = \bar{\delta}(N, \nu, \varepsilon) > 0$ such that the following hold. For every $\delta \in [0, \bar{\delta}]$, if (X, d, m) is an $RCD(N - 1 - \delta, N + \delta)$ space satisfying

$$\mathcal{I}_{(X,d,m)}(\nu) \leq \mathcal{I}_{N-1,N,\pi}(\nu) + \delta,$$

then there exists an $RCD(N - 2, N - 1)$ space (Y, d_Y, m_Y) with $m_Y(Y) = 1$ such that

$$d_{mGH}(X, [0, \pi] \times_{\sin}^{N-1} Y) \leq \varepsilon.$$

RK The almost rigidity seems new even for smooth manifolds:

if (M^n, g) has $Ric_g \geq (n - 1 - \delta)g$ and

$\mathcal{I}_{(M,d_g, vol/vol(M))}(\nu) \leq \mathcal{I}_{N-1,N,\pi}(\nu) + \delta$ then (M^n, g) is mGH -close to a spherical suspension. \rightsquigarrow an example of application of RCD spaces to smooth manifolds with lower Ricci bounds.

- ▶ **Step 1** making quantitative the arguments of the rigidity theorem we get that the diameter of X must be almost maximal, more precisely: for every $N \in [2, \infty)$, $\nu \in (0, 1)$, $\eta > 0$ there exists $\bar{\delta} = \bar{\delta}(N, \nu, \eta) > 0$ such that if (X, d, m) is an $RCD(N - 1 - \delta, N + \delta)$ space satisfying $\mathcal{I}_{(X, d, m)}(\nu) \leq \mathcal{I}_{N-1, N, \infty}(\nu) + \delta$, for some $\delta \leq \bar{\delta}$ then $\text{diam}(X) \geq \pi - \eta$.
- ▶ **Step 2** conclude by a compactness-contradiction argument:
 - ▶ Assume by contradiction there exist $\varepsilon_0 > 0$ and a sequence (X_j, d_j, m_j) of $RCD(N - 1 - \frac{1}{j}, N + \frac{1}{j})$ spaces such that $\mathcal{I}_{(X_j, d_j, m_j)}(\nu) \leq \mathcal{I}_{N-1, N, \infty}(\nu) + \frac{1}{j}$ but $d_{mGH}(X_j, [0, \pi] \times_{\sin}^{N-1} Y) \geq \varepsilon_0$ for every $j \in \mathbb{N}$ and every $RCD(N - 2, N - 1)$ space (Y, d_Y, m_Y) with $m_Y(Y) = 1$.
 - ▶ Then by Step 1 we get $\text{diam}(X_j) \rightarrow \pi$
 - ▶ by Gromov's compactness Theorem + stability of $RCD(N - 1, N)$ there exists an $RCD(N - 1, N)$ space $(X_\infty, d_\infty, m_\infty)$ such that, up to subsequences, $X_j \rightarrow X_\infty$ in mGH -sense.
 - ▶ by since diam is continuous under mGH -convergence, we get $\text{diam}(X_\infty) = \pi$, so by Max Diam Thm X_∞ is a spherical suspension; contradiction.

Further results via 1-D localization

In a second paper still in collaboration with Cavalletti we used 1-D localization to prove further inequalities, many of them answer open problems proposed by Villani in its celebrated book "Optimal transport: old and new".

If (X, d, m) is $RCD(K, N)$ with $K > 0$, then

► p -spectral gap: Let

$$\lambda_{(X,d,m)}^{1,p} = \inf \left\{ \frac{\int_X |\nabla f|^p dm}{\int_X |f|^p dm} : f \neq 0, \int_X f |f|^{p-2} dm = 0 \right\},$$

then $\lambda_{(X,d,m)}^{1,p} \geq \lambda_{K,N}^{1,p}$, with " $=$ " iff X is a spherical suspension, and "almost $=$ " iff X is mGH -close to a spherical suspension.

► Dimensional improvement of Log-Sobolev

for any $f : X \rightarrow [0, \infty)$ with $\int_X f dm = 1$ it holds

$$2 \frac{KN}{N-1} \int_X f \log f dm \leq \int_{\{f>0\}} \frac{|\nabla f|^2}{f} dm,$$

► Sharp Sobolev

$$\frac{KN}{(p-2)(N-1)} \left\{ \left(\int_X |f|^p dm \right)^{\frac{2}{p}} - \int_X |f|^2 dm \right\} \leq \int_X |\nabla f|^2 dm,$$

Euclidean tangents to $RCD(K, N)$ spaces

- ▶ Cheeger-Colding '97: for limit spaces the local blow ups are a.e. unique and euclidean.
- ▶ **Q:** is it true also for $RCD(K, N)$ spaces?
- ▶ **Notation** Fixed $\bar{x} \in X$, call $Tan(X, d, \mathfrak{m}, \bar{x})$ the set of local blow ups (also called tangent cones) of X at \bar{x} .
- ▶ More precisely, for $r \in (0, 1)$ consider the p.m.m.s. $(X, r^{-1}d, \mathfrak{m}(B_r(\bar{x}))^{-1} \cdot \mathfrak{m}, \bar{x})$.
Given any sequence $r_n \downarrow 0$, by Gromov compactness, there exists a subsequence $r_{n_k} \downarrow 0$ and a limit space $(Y, d_Y, \mathfrak{m}_Y, \bar{y})$ such that $(X, r_{n_k}^{-1}d, \mathfrak{m}(B_{r_{n_k}}(\bar{x}))^{-1} \cdot \mathfrak{m}, \bar{x}) \rightarrow (Y, d_Y, \mathfrak{m}_Y, \bar{y})$.
By definition $Tan(X, d, \mathfrak{m}, \bar{x})$ is the set of all these limit spaces $(Y, d_Y, \mathfrak{m}_Y, \bar{y})$.

Existence of Euclidean tangents

THM 1 [Gigli-M.-Rajala '13] Let (X, d, \mathfrak{m}) be an $RCD(K, N)$ space. Then for \mathfrak{m} -a.e. $x \in X$ there exists $n = n(x) \in \mathbb{N}$, $n \leq N$, such that

$$(\mathbb{R}^n, d_E, \mathcal{L}_n, 0) \in \text{Tan}(X, d, \mathfrak{m}, x),$$

where d_E is the Euclidean distance and \mathcal{L}_n is the n -dimensional Lebesgue measure normalized so that $\int_{B_1(0)} 1 - |x| d\mathcal{L}_n(x) = 1$.

Idea of proof

The **key technical tool** of the proof is the **Splitting theorem** in $RCD(0, N)$ spaces by Gigli (non smooth generalization of the classical Cheeger-Gromoll Splitting Thm)

1. \mathfrak{m} -a.e. $\bar{x} \in X$ is the midpoint of some geodesic
2. Take a sequence of blow ups at such \bar{x} , by Gromov compactness and by Stability they converge to a limit $RCD(0, N)$ space $(Y, d_Y, \mathfrak{m}_Y, \bar{y}) \in \text{Tan}(X, d, \mathfrak{m}, \bar{x})$
3. By the choice of \bar{x} , Y contains a line and therefore splits an \mathbb{R} factor, by the splitting thm: $Y \cong Y' \times \mathbb{R}$
4. Repeating the construction for Y' in place of X we get that there exists a local blow up \tilde{Y}' of Y' that splits an \mathbb{R} factor: $\tilde{Y}' = Y'' \times \mathbb{R}$
5. Adapting ideas of Preiss (and of Le Donne) we prove that \mathfrak{m} -a.e. tangents of tangents are tangent themselves, i.e. $Y'' \times \mathbb{R}^2 = \tilde{Y}' \times \mathbb{R} \in \text{Tan}(X, d, \mathfrak{m}, \bar{x})$
6. repeating the scheme iteratively we conclude.

Further structure of $RCD(K, N)$ spaces

Q: In the previous Thm we have **existence** of a euclidean tangent cone; but is the tangent cone **unique**?

THM 2[Naber-M.'14] Let (X, d, m) be an $RCD(K, N)$ space. Then for m -a.e. $x \in X$ the tangent cone IS UNIQUE and euclidean, i.e. there exists $n = n(x) \in \mathbb{N}$, $n \leq N$, such that

$$\{(\mathbb{R}^n, d_E, \mathcal{L}_n, 0)\} = \text{Tan}(X, d, m, x),$$

More precisely we have

THM 3[Naber-M.'14] [Rectifiability of $RCD(K, N)$ -spaces] Let (X, d, m) be an $RCD(K, N)$ space. Then, for every $\varepsilon > 0$ there exists a countable collection $\{R_j^\varepsilon\}_{j \in \mathbb{N}}$ of m -measurable subsets of X , covering X up to an m -negligible set, such that each R_j^ε is $1 + \varepsilon$ -biLipshitz to a measurable subset of \mathbb{R}^{k_j} , for some $1 \leq k_j \leq N$, k_j possibly depending on j .

Preliminary remarks

- ▶ If X is a **Ricci limit space**, Thm 2 was first proved by Cheeger-Colding '00: prove hessian estimates on harmonic approximations of distance functions, and use these to force splitting behavior.
- ▶ In the context of general metric spaces the notion of a hessian is still not at the same level as it is for a smooth manifold, and cannot be used in such strength (interesting work of Gigli in this direction though).
- ▶ So we prove entirely **new** estimates, both in the form of **gradient estimates on the excess function** and a **new almost splitting theorem with excess**, which will allow us to use the distance functions directly as our chart maps. New even in the smooth context.

Strategy of proof, 1: the A_k 's.

Define

$$A_k := \{x \in X : \exists \text{ a tangent cone of } X \text{ at } x \text{ equal to } \mathbb{R}^k \text{ but no tangent cone at } x \text{ splits } \mathbb{R}^{k+1}\}.$$

We first prove that

- A_k is \mathfrak{m} -measurable (it is difference of analytic sets),
- by THM 1 we get $\mathfrak{m}(X \setminus \bigcup_{k \in \mathbb{N}} A_k) = 0$.

So THM 2-3 are a consequence of the following

THM 4. Let (X, d, \mathfrak{m}) be an $RCD(K, N)$ -space, and let A_k be as above. Then

- (1) For \mathfrak{m} -a.e. $x \in A_k$ the tangent cone of X at x is unique and isomorphic to the k -dimensional euclidean space.
- (2) There exists $\bar{\varepsilon} = \bar{\varepsilon}(K, N) > 0$ such that, for every $0 < \varepsilon \leq \bar{\varepsilon}$, A_k is k -rectifiable via $1 + \varepsilon$ -biLipschitz maps. More precisely, for each $\varepsilon > 0$ we can cover A_k , up to an \mathfrak{m} -negligible subset, by a countable collection of sets U_ε^k with the property that each one is $1 + \varepsilon$ -biLipschitz to a subset of \mathbb{R}^k .

Strategy of proof, 2: rough idea

1. Given $\bar{x} \in A_k$, for every $0 < \delta \ll 1$ there exists $r > 0$ such that $d_{mGH}(B_{\delta^{-1}r}(\bar{x}), (B_{\delta^{-1}r}(0^k))) \leq \delta r$.
2. For some radius $r \ll R \ll \delta^{-1}r$ we can then pick points $\{p_i, q_i\}_{i=1, \dots, k} \in X$ corresponding to the bases $\pm Re_i$ of \mathbb{R}^k .
Define the map
$$\vec{d} = \left(d(p_1, \cdot) - d(p_1, \bar{x}), \dots, d(p_k, \cdot) - d(p_k, \bar{x}) \right) : B_r(\bar{x}) \rightarrow \mathbb{R}^k.$$
For δ sufficiently small, \vec{d} is a εr -mGH map $B_r(\bar{x}) \rightarrow B_r(0^k)$.
3. **MAIN CLAIM:** \exists a set $U_\varepsilon \subseteq B_r(\bar{x})$ of almost full measure, i.e. $m(B_r(\bar{x}) \setminus U_\varepsilon) \leq \varepsilon$, s.t. $\forall x \in U_\varepsilon$ and $s \leq r$, the restriction map $\vec{d} : B_s(x) \rightarrow \mathbb{R}^k$ is an εs -measured Gromov Hausdorff map.
4. From this we can show that the restriction map $\vec{d} : U_\varepsilon \rightarrow \mathbb{R}^k$ is in fact $1 + \varepsilon$ -bilipschitz onto its image. By covering A_k with such sets we will show that A_k is itself rectifiable.

Strategy of proof, 3: two new ingredients

Define $e_{p,q}(y) := d(p, y) + d(q, y) - d(p, q)$, called excess function. In order to get the main claim, two new ingredients

1. **Gradient Excess Estimates.** We show that the gradient of the excess functions e_{p_i, q_i} of the points $\{p_i, q_i\}$ is small in L^2 , more precisely: for the above $\delta > 0$ small enough, then

$$\int_{B_r(\bar{x})} |De_{p_i, q_i}|^2 dm \leq \varepsilon_1.$$

2. **Almost splitting via excess:** given $x \in B_r(\bar{x})$ and $s \in (0, r)$, if $\int_{B_s(x)} |De_{p_i, q_i}|^2 dm < \varepsilon_1$, then

$$d_{mGH} \left(B_s(x), B_s^{\mathbb{R} \times Y}((0, y)) \right) < \varepsilon_2 s,$$

for some m.m.s. (Y, d_Y, m_Y, y) .

I.e.: gradient of excess small in $L^2 \Rightarrow$ close to a splitting.

Proof by contradiction, in the limit we enter into the framework of the arguments of Splitting Theorem.

Strategy of proof, 4: construction of U_ε

Construction via a maximal function argument: for $x \in B_r(\bar{x})$ call

$$M(x) := \sup_{s \in (0, r)} \sum_{i=1}^k \int_{B_s(x)} |De_{p_i, q_i}|^2 d\mathbf{m}.$$

Define

$$U_\varepsilon := \{x \in B_r(\bar{x}) : M(x) < \varepsilon\}.$$

By the Gradient Excess Estimates+ $L^1 \rightarrow L^{1, weak}$ continuity of maximal function operator

\Rightarrow for $\delta > 0$ small enough we have $\mathbf{m}(B_r(\bar{x}) \setminus U_\varepsilon) < \varepsilon$.

But $\forall x \in U_\varepsilon, \forall s \leq r$, by construction,

$\sum_{i=1}^k \int_{B_s(x)} |De_{p_i, q_i}|^2 d\mathbf{m} \leq \varepsilon s$. An iteration of the almost splitting theorem via excess estimates implies then that

$$d_{mGH}(B_s(x), B_s(0^k)) \leq \varepsilon_2 s, \quad \forall s \leq r \quad \Rightarrow \quad \text{Main claim.}$$

Challenges for the future

- ▶ As Alexandrov spaces played a crucial role to establish new theorem for smooth manifolds with lower sectional curvature bounds, we expect $RCD(K, N)$ spaces to be useful to give new insights for smooth manifolds with lower Ricci bounds.
- ▶ For Ricci limits, Colding-Naber '11 and Kapovitch-Li '15 proved that the dimension of the euclidean tangent space is constant a.e. Is it true also also for $RCD(K, N)$ spaces?
- ▶ Is it true that any $RCD(K, N)$ space is a Ricci limit?
- ▶ Is it true that any $RCD(1, 2)$ space is Alexandrov with $\text{curv} \geq 1$?
- ▶ "Ricci flow" for metric measure spaces? Some interesting recent insights by Haslhofer-Naber, Kleiner-Lott, Lott, Gigli-Mantegazza, Sturm,...

!!THANK YOU FOR THE
ATTENTION!!